

# Micro-Geomechanics Across Multiple Strain Scales

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Unresolved scale-dependent phenomena:

1. Spontaneous localization
2. Dependence of stiffness on gradients of strain
3. Effect of confining pressure and inter-particle friction on mechanical behavior
4. Material softening

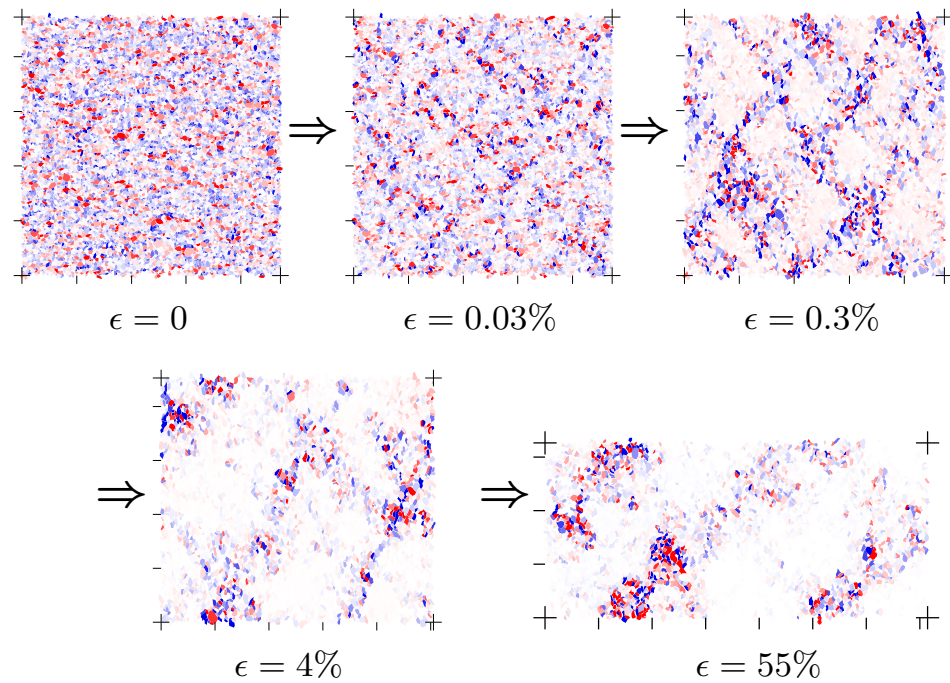
Characteristics common to these phenomena:

- Predominant at moderate to large strains
- Accompanied by rapid particle rotations and rolling
- Particle motions deviate greatly from uniform deformation
- Sensitive to particle shapes

**Example: Localization and patterning at multiple strain scales.**

**Biaxial compression of 4000 ovals.**

**Cluster dilations.**



## Granular stiffness is geometric as well as mechanical

**Example: Behavior of particle pairs at the peak and steady states**

$$\bar{\sigma} = \frac{1}{V} \sum_{\text{pairs}} \mathbf{l} \otimes \mathbf{f}$$

$$\frac{d\bar{\sigma}}{d\epsilon} = 0 \quad \Rightarrow \quad \text{stationary stress}$$

**Stress increment**

$$d\bar{\sigma} = \overset{\boxed{1}}{-\frac{dV}{V}\bar{\sigma}} + \overset{\boxed{2}}{\frac{1}{V} \sum_{\text{pairs}} \mathbf{l} \otimes d\mathbf{f}} + \overset{\boxed{3}}{\frac{1}{V} \sum_{\text{pairs}} d\mathbf{l} \otimes \mathbf{f}}$$

**Results: Changes in the contact forces produce hardening.  
Changes in the contact directions produce softening.**

**Conclusions:**

- Granular stiffness likely depends on the particle shapes at their contacts.
- Granular stiffness has both mechanical and geometric origins.

Possible framework for granular stiffness at the scales of particle pairs/clusters/assemblies:

$$\begin{bmatrix} \mathbf{H} \end{bmatrix} \begin{bmatrix} \frac{d\mathbf{u}}{d\theta} \end{bmatrix} = \begin{bmatrix} \frac{d\mathbf{f}}{d\mathbf{m}} \end{bmatrix}$$

Stiffness  $[\mathbf{H}]$  has both mechanical and geometric parts:

$$\begin{bmatrix} \mathbf{H} \end{bmatrix} = \begin{bmatrix} \mathbf{H}^{\text{mechanical}} \end{bmatrix} + \begin{bmatrix} \mathbf{H}^{\text{geometric}} \end{bmatrix}$$

Stability and softening are associated with second-order work:

$$\Delta_2 W = \left[ \frac{d\mathbf{u}}{d\theta} \right]^T \begin{bmatrix} \mathbf{H} \end{bmatrix} \begin{bmatrix} \frac{d\mathbf{u}}{d\theta} \end{bmatrix}$$

Example: Softening before and after shear band formation

