

# Micro-Mechanics of Granular Flow at Large Strains

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# Introduction

Granular “genre”:

Dense packings

Slow loading

Granular phenomena at large strains:

- Reduced stiffness
- Softening
- Localized deformation
- Non-coaxiality,  $d\boldsymbol{\sigma} \leftrightarrow d\boldsymbol{\epsilon}$
- Gradient effects,  $d\boldsymbol{\sigma} \leftrightarrow \nabla_x \boldsymbol{\epsilon}$

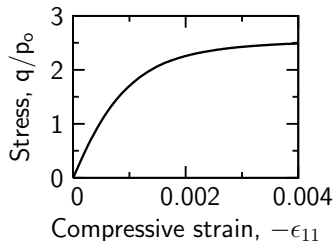
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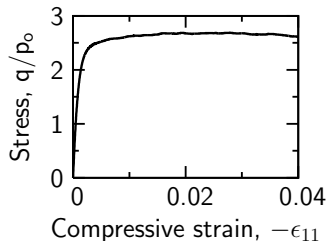
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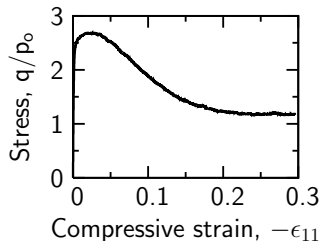
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# Three views of large-strain micro-mechanics

Three approaches to micro-mechanics:

- 1 Discrete contact approach
- 2 Contact distribution approach
- 3 Discrete stiffness approach

Focus on

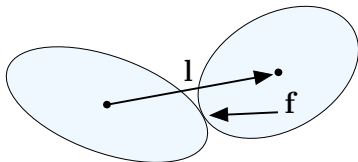
- Incremental behavior
- “Mechanical” vs. “Geometric” effects
- Large vs. small strains

# Outline

- 1 **Micro-view 1: Discrete contact approach**
  - Average stress
  - Example
- 2 Micro-view 2: Contact distribution approach
- 3 Micro-view 3: Discrete stiffness approach

# Discrete contact approach

Calculation of average stress

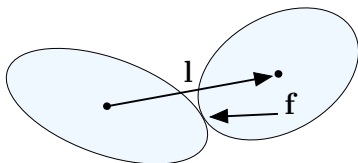


$$\sigma = \frac{1}{V} \sum \mathbf{l} \otimes \mathbf{f}$$



# Discrete contact approach

Calculation of **stress increment**

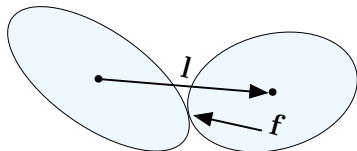


$$\sigma = \frac{1}{V} \sum \mathbf{l} \otimes \mathbf{f}$$

$$d\sigma = -\frac{dV}{V}\sigma + \underbrace{\frac{1}{V} \sum \mathbf{l} \otimes d\mathbf{f}}_{\text{Mechanical}} + \underbrace{\frac{1}{V} \sum d\mathbf{l} \otimes \mathbf{f}}_{\text{Geometric}}$$

# Discrete contact approach

Calculation of **stress increment**

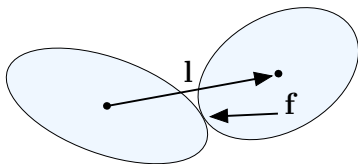


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# Discrete contact approach

Calculation of **stress increment**

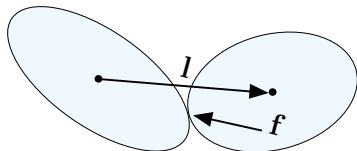


$$\sigma = \frac{1}{V} \sum \mathbf{l} \otimes \mathbf{f}$$

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# Discrete contact approach

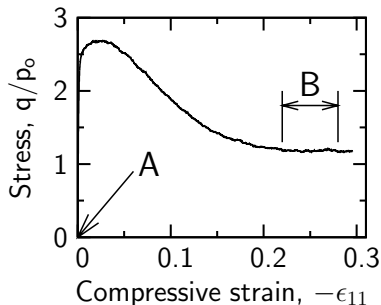
Calculation of **stress increment**



$$\sigma = \frac{1}{V} \sum \mathbf{l} \otimes \mathbf{f}$$

$$d\sigma = -\frac{dV}{V}\sigma + \underbrace{\frac{1}{V} \sum \mathbf{l} \otimes d\mathbf{f}}_{\text{Mechanical}} + \underbrace{\frac{1}{V} \sum d\mathbf{l} \otimes \mathbf{f}}_{\text{Geometric}}$$

## Discrete contact approach — Example

Stress rates during loading,  $d\sigma / d\epsilon$ 

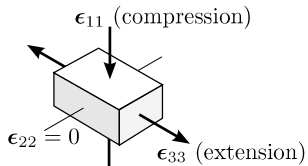
	A	B
Mechanical	+2,253	+4.1
Geometric	-1.9	-4.1
$\Sigma =$	+2,251	0

# Outline

- 1 Micro-view 1: Discrete contact approach
- 2 **Micro-view 2: Contact distribution approach**
  - Force anisotropy
  - Contact migration
  - Stress rate
  - Example
- 3 Micro-view 3: Discrete stiffness approach

# Contact distribution approach

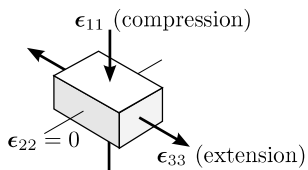
Contact force anisotropy during loading:



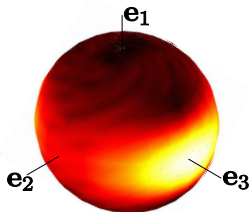
Plane strain biaxial  
loading

# Contact distribution approach

Contact force anisotropy during loading:



Plane strain biaxial  
loading

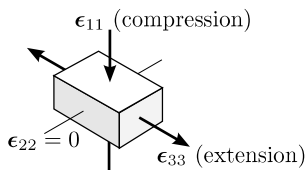


Force density

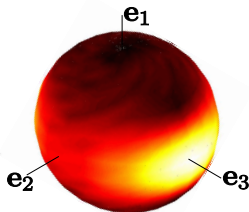


# Contact distribution approach

Contact force anisotropy during loading:



Plane strain biaxial loading



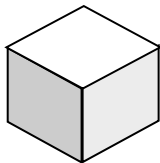
Force density

Density  
 $\hat{f}(\mathbf{n})$

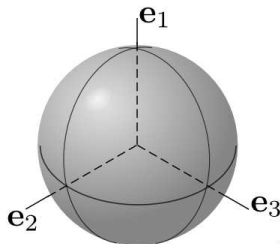
Density  
 rate?

# Contact distribution approach

Migration of contacts?



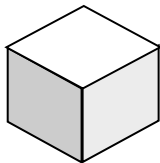
Assembly box



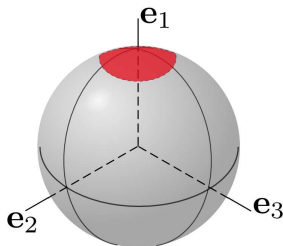
Unit sphere,  $\Omega$

# Contact distribution approach

Migration of contacts?



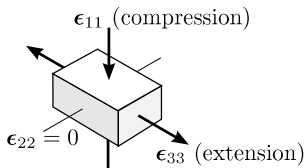
Assembly box



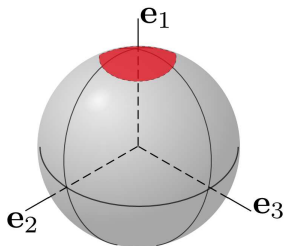
Contact set

# Contact distribution approach

Migration of contacts?



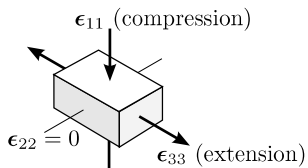
Plane strain biaxial  
loading



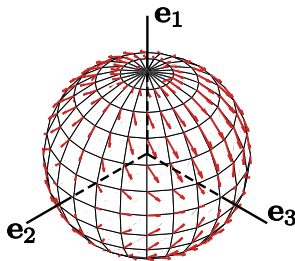
Contact set

# Contact distribution approach

Migration of contacts?



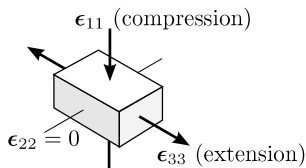
Plane strain biaxial loading



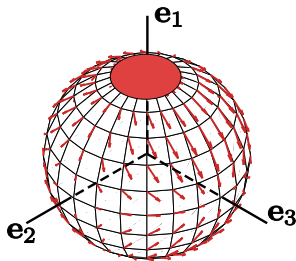
Prevailing migration  $\dot{n}(\mathbf{n})$

# Contact distribution approach

Migration of contacts?

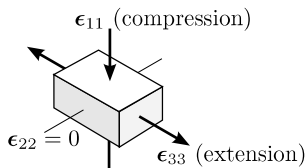


Plane strain biaxial loading

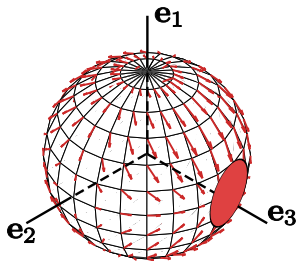


# Contact distribution approach

Migration of contacts?

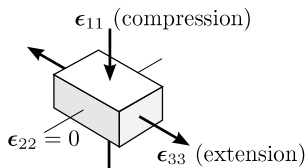


Plane strain biaxial loading

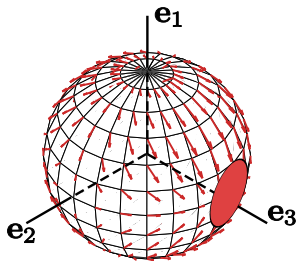


# Contact distribution approach

Migration of contacts?



Plane strain biaxial loading





# Stress & force evolution

Force distribution rate:

$$\left. \frac{\partial \hat{\mathbf{f}}(\mathbf{n})}{\partial t} \right|_{\mathbf{n}} = \underbrace{\left( \frac{\partial \hat{\mathbf{f}}(\mathbf{n})}{\partial t} \right)_{\text{matl}}}_{\text{1}} - \underbrace{\nabla \cdot (\dot{\mathbf{n}} \hat{\mathbf{f}}(\mathbf{n}))}_{\text{2}} + \underbrace{\left( \frac{\partial \hat{\mathbf{f}}(\mathbf{n})}{\partial t} \right)_{\text{diffusion}}}_{\text{3}}$$

Matl. rate

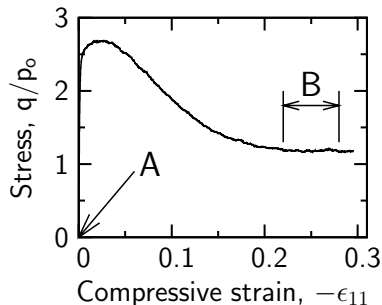
Divergence /  
convection

Diffusion

Ma and Zhang (2006)

# Contact distribution approach — Example

Stress rates during loading,  $d\sigma / d\epsilon$



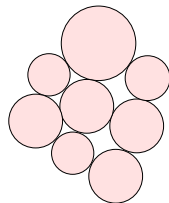
	A	B
Mechanical	+3,510	+4.0
Geometric	-2	-4.0
$\Sigma =$	+3,508	0

# Outline

- 1 Micro-view 1: Discrete contact approach
- 2 Micro-view 2: Contact distribution approach
- 3 Micro-view 3: Discrete stiffness approach**
  - Incremental stiffness
  - Examples
  - Pathologies I
  - Pathologies II

# Discrete stiffness approach

Incremental stiffness of a particle assembly:



Particle  
movements

$[d\mathbf{u}]$

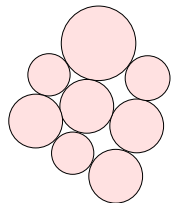


External  
forces

$[d\mathbf{f}]$

# Discrete stiffness approach

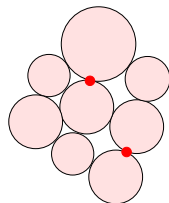
Incremental stiffness of a particle assembly:



$$[\mathbf{K}][d\mathbf{u}] = [d\mathbf{f}]$$

# Discrete stiffness approach

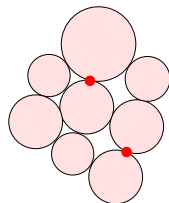
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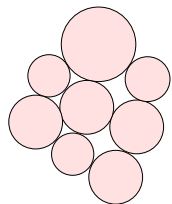
Incremental stiffness of a particle assembly:



$$\begin{aligned} [\mathbf{K}^{\bullet,\bullet}] [d\mathbf{u}] &= [d\mathbf{f}] \\ [\mathbf{K}^{\circ,\bullet}] [d\mathbf{u}] &= [d\mathbf{f}] \\ [\mathbf{K}^{\bullet,\circ}] [d\mathbf{u}] &= [d\mathbf{f}] \\ [\mathbf{K}^{\circ,\circ}] [d\mathbf{u}] &= [d\mathbf{f}] \end{aligned}$$

# Discrete stiffness approach

Incremental stiffness of a particle assembly:

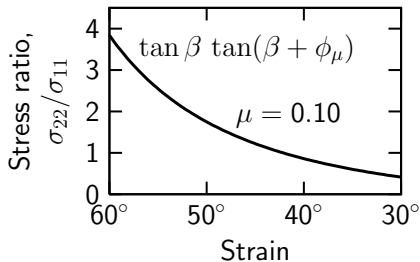
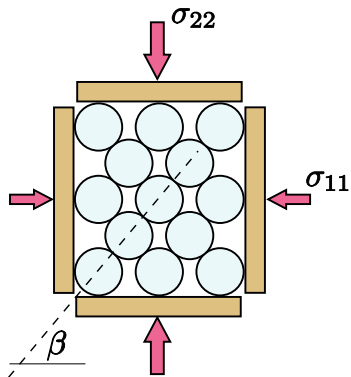


$$\left( [\mathbf{K}^{\text{Mech.}}] + [\mathbf{K}^{\text{Geom.}}] \right) [d\mathbf{u}] = [d\mathbf{f}]$$



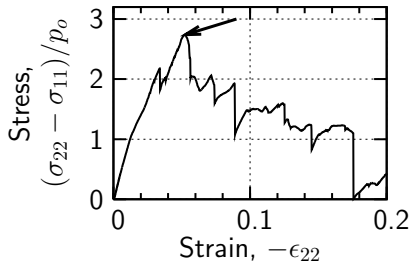
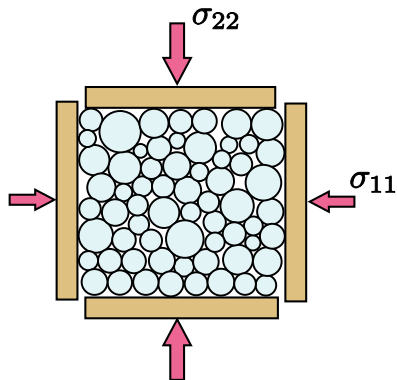
# Discrete stiffness approach — Example I

Example I: Regular array



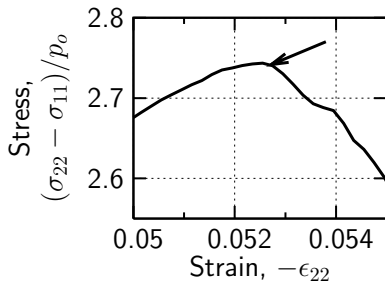
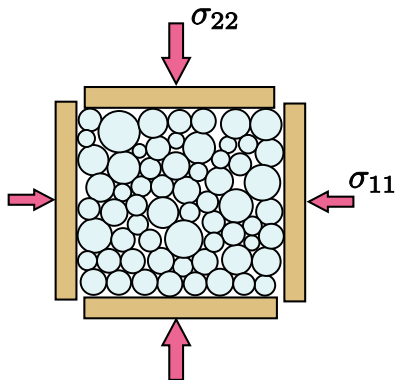
# Discrete stiffness approach — Example II

Example II: Assembly of 64 disks



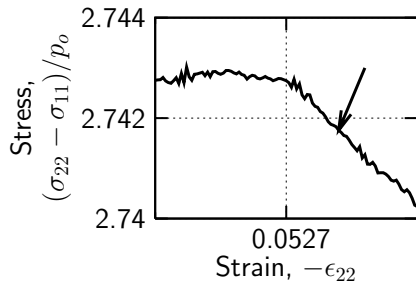
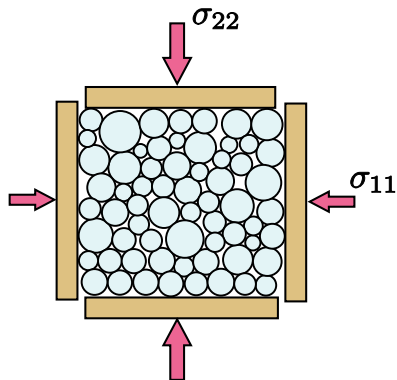
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Example II: Assembly of 64 disks



# Discrete stiffness approach — Example II

Example II: Assembly of 64 disks



# Discrete stiffness approach

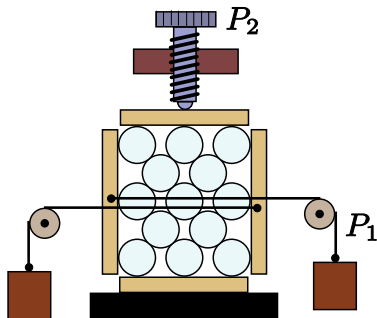
$$[\mathbf{K}][d\mathbf{u}] = [d\mathbf{f}]$$

Stiffness “pathologies”:

- 1 Softening
- 2 External instability
- 3 Internal instability
- 4 Non-uniqueness / bifurcation

# Discrete stiffness approach — Example I

## Pathology 1: Softening



Softening

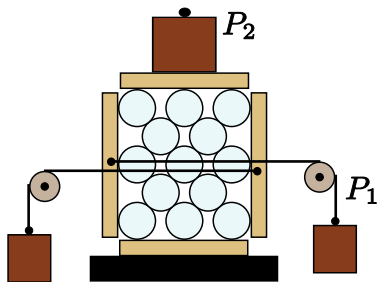
$$\delta^2 W = dP_1 dl_1 + dP_2 dl_2 < 0$$

Externally stable

Softening is entirely **geometric!**

# Discrete stiffness approach — Example I

## Pathology 2: External instability



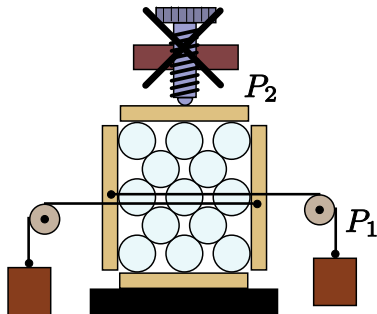
Externally unstable

$$\delta^2 W = dP_1 dl_1 + dP_2 dl_2 < 0$$

Collapse

# Discrete stiffness approach — Example I

## Pathology 3: Internal instability



Externally stable

Internally unstable

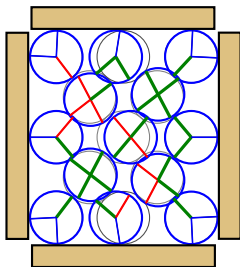
$$\delta^2 W = [d\mathbf{u}]^T [\mathbf{K}][d\mathbf{u}] < 0$$



# Discrete stiffness approach — Example I

## Pathology 3: Internal instability

### Example instability mode



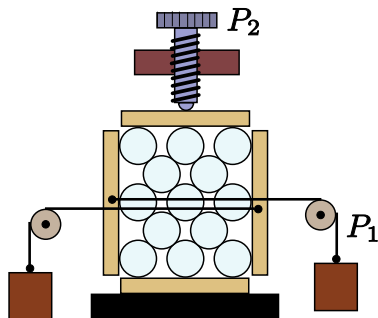
Externally stable

Internally unstable

$$\delta^2 W = [d\mathbf{u}]^T [\mathbf{K}] [d\mathbf{u}] < 0$$

# Discrete stiffness approach — Example I

## Pathology 4: Non-uniqueness / bifurcation



Softening

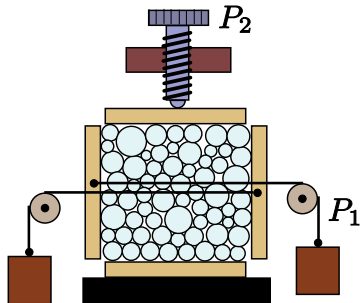
$$\delta^2 W = dP_1 dl_1 + dP_2 dl_2 < 0$$

Externally stable

Solution is **unique** !

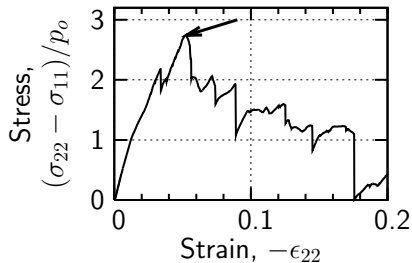
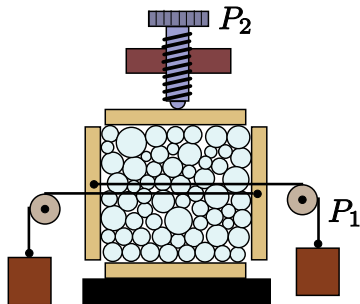
## Discrete stiffness approach — Example II

Example II: Assembly of 64 disks



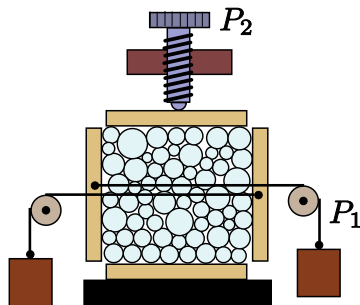
# Discrete stiffness approach — Example II

Example II: Assembly of 64 disks



# Discrete stiffness approach — Example II

Example II: Assembly of 64 disks



(1) Softening

$$\delta^2 W = dP_1 dl_1 + dP_2 dl_2 < 0$$

Softening is **geometric**

(2) Externally stable

(3) Internally unstable

At least six unstable modes

$$\delta^2 W = [d\mathbf{u}]^T [\mathbf{K}] [d\mathbf{u}] < 0$$

(4) Unique solution

# Conclusions

# Questions?